國立成功大學 110學年度碩士班招生考試試題

編 號: 131

系 所: 航空太空工程學系

科 目: 工程力學

日 期: 0202

節 次:第2節

備 註:不可使用計算機

編號: 131

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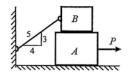
考試科目:工程力學

考試日期:0202,節次:2

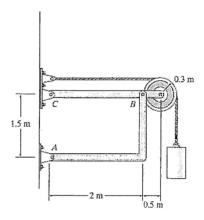
第1頁,共2頁

※ 考生請注意:本試題不可使用計算機。 請於答案卷(卡)作答,於本試題紙上作答者,不予計分。

- 1. The weights of blocks A and B are, respectively, $W_A = 400 \text{ N}$ and $W_B = 340 \text{ N}$. Block B is held to a wall by a cable. The coefficient of static friction at all surfaces of contact is 0.2.
 - (a) (10%) Draw the free-body diagrams of block A and of block B.
 - (b) (10%) Determine the force P needed to move block A.



2. (20%) Determine the horizontal and vertical components of force at pins B and C. The suspended cylinder has a weight of 240 N. The pulley is frictionless, and the weights of members AB and BC are neglected. Hint: identify if there is any two-force member.



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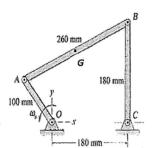
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第2頁,共2頁

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 - 3. (10%) In the four-bar linkage shown, the control link OA has a counter-clockwise constant angular velocity $\omega_0 = 1 \, \text{rad/s}$.

At the instant when point A is on coordinates (-60, 80), link BC is vertical, and link AB is 22.6° from the horizontal, cos (22.6°) = 0.923 and sin (22.6°) = 0.385, calculate

- (1) the angular velocity of link AB,
- (2) the angular acceleration of AB, and
- (3) the velocity of point G at the midpoint of AB.



- 4. Continue on the four-bar linkage shown above in gravitation filed (-y direction) with a torque applied M on the control link OA. Assume all links are uniform with mass center located at each of the midpoint. Link OA, AB, and BC each has mass m₁, m₂, and m₃, mass moment of inertia I₁, I₂, and I₃.
 - (1) Draw the free body diagram of each link and denote all the reaction forces. (9%)
 - (2) Write the equation of motion governing the rigid body motion of each link. (9%)
 - (3) Specify the unknowns in the equations of (2). How many unknowns? (5%)
 - (4) State (no derivation) the extra equations needed in order to solve for all the unknowns. (7%)
- 5. The rectangular plate of uniform small thickness with mass m kg is welded at θ angle (θ = 45°, the angle between the z-axis and the plate plane) to the midpoint of a vertical shaft of negligible mass and length L rotating at constant angular velocity ω rad/s. Determine
 - (1) the mass moment inertia about x-y-z coordinates of the plate, (5%)
 - (2) the angular momentum H of the plate about x-y-z coordinates, (5%)
 - (3) the kinetic energy of the plate, (5%)
 - (4) the moment M applied to the shaft due to dynamic imbalance (5%)

