

1997 碩士班入學考試

1.

Consider the following system with $G(s) = \frac{30}{s^3 + 11s^2 + 10s}$.

(a) Plot the Bode plot of $G(s)$. (10%)

(b) Determine the parameters of the controller $C(s) = \frac{k(s+z)}{(s+p)}$ by root locus method, such that the dominant closed loop poles are located at $-2 \pm 2j$. (15%)

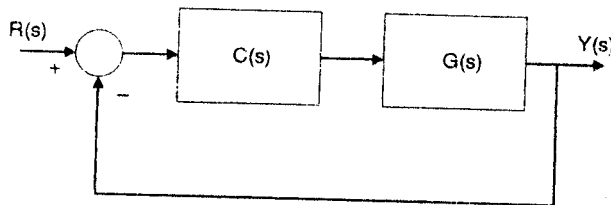


Fig.1

2. (25%)

Determine the system transfer function $G(s)$ using the following step input time response, and plot the corresponding Nyquist plot. Determine the range of k such that the closed-loop system is stable.

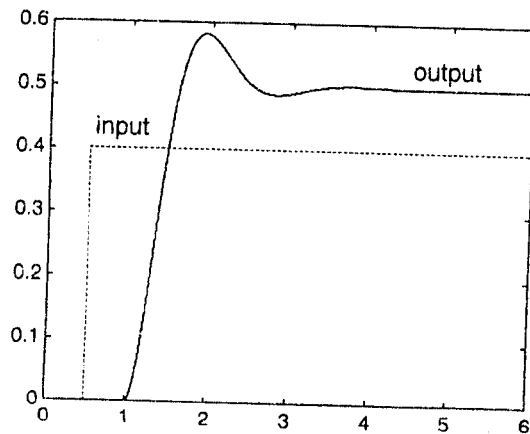


Fig.2-1. Step input response

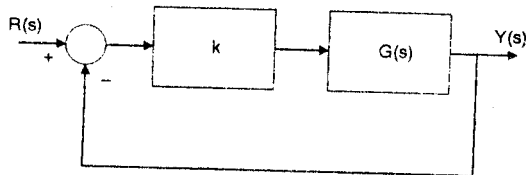


Fig.2-2.

Linear Control

Problem 3, 20%

Find the transfer function from u to y , for the control system shown below.

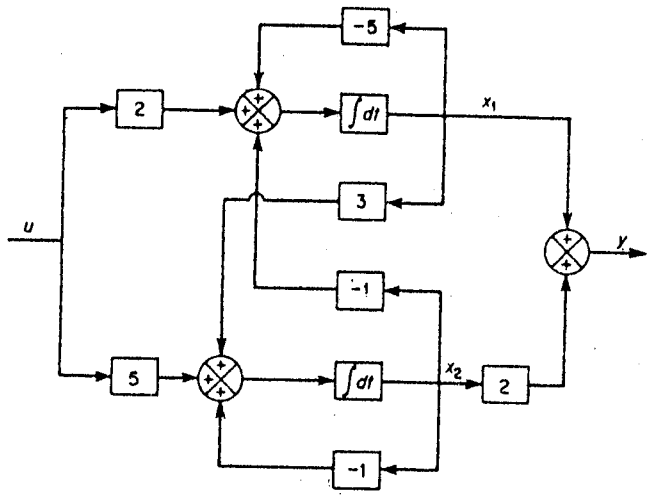


Figure of Problem 3

Problem 4, 30%

(A) Consider linear system

$$\dot{x} = Ax + Bu$$

where $x \in \mathbb{R}^{n \times 1}$, $u \in \mathbb{R}^{r \times 1}$, $A \in \mathbb{R}^{n \times n}$, $B \in \mathbb{R}^{n \times r}$.

Now, assume input $u(t)$ is given, show the solution $x(t)$ can be derived as

$$x(t) = e^{At} x(0) + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$

(B) Use the above formula to find the solution of the following system

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} u, \quad x_1(0) = x_2(0) = 0$$

where $u(t) = 1, t \geq 0$.