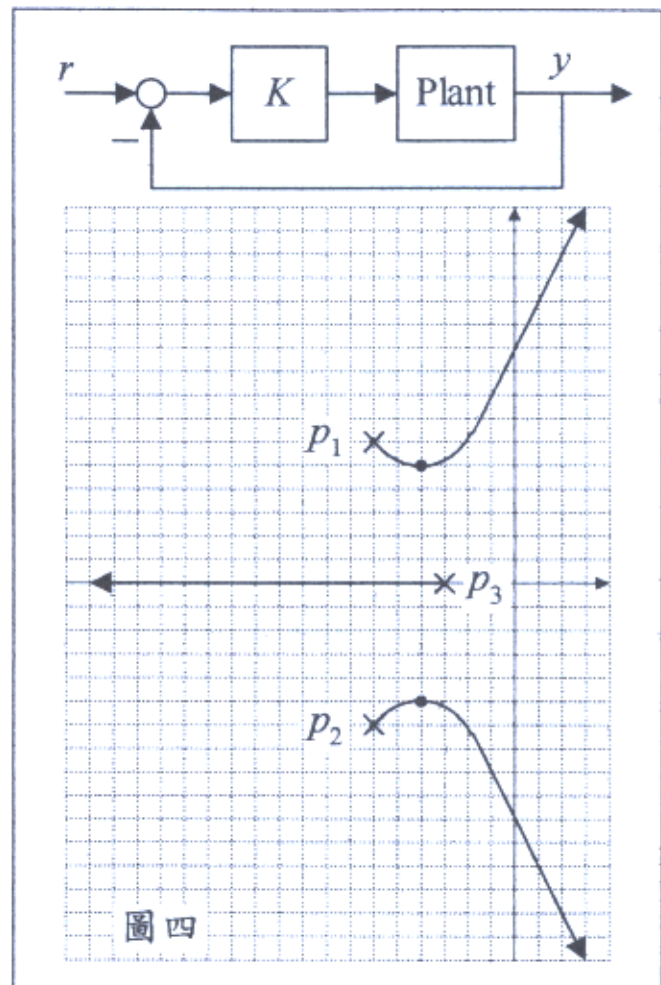


- 1) A feedback control system has the following characteristic equation:

$$s^3 + (4 + K)s^2 + 6s + 16 + 8K = 0.$$

The parameter  $K$  must be positive. What is the maximum value  $K$  can assume before the system becomes unstable?(15%) When  $K$  is equal to the maximum value, the system oscillates. Determine the frequency of this oscillation. (10%)

- 2) 右圖為一個迴饋控制系統以及它的閉迴路根軌跡；其中， $p_1$ 、 $p_2$ 及 $p_3$ 分別為開迴路系統的三個極點，而兩個圓點則為所欲的閉迴路 dominant mode 極點。求這個設計的 Gain margin (15%)。(注意：座標的尺寸並不影響答案。)



(背面仍有題目,請繼續作答)

3. (25%) Plot the Bode plot of the following transfer function  $G(s)$  and

check the stability of the closed-loop system  $T(s) = \frac{G(s)}{1+G(s)}$  using

the Nyquist stability criterion, where

$$G(s) = \frac{k(-s+5)}{s(s+10)}, \text{ with } k = 8$$

4. (15%) Determine the closed-loop bandwidth and calculate the phase and gain margins with  $k = 5$ .

5. (20%) Consider the system described by the following differential equations.

$$L \frac{di(t)}{dt} = e(t) - Ri(t) - e_b(t)$$

$$T_m(t) = K i(t)$$

$$e_b(t) = K_b \frac{d\theta(t)}{dt} = K_b \omega(t)$$

$$J \frac{d^2\theta(t)}{dt^2} = T_m(t) - T_L(t) - B \frac{d\theta(t)}{dt}$$

(a). Choose  $[i(t) \ \omega(t) \ \theta(t)]$  as the system states, and represent the system by its state-space form.

(b). Determine the system transfer function from  $T_L(t)$  to  $\theta(t)$ .

(c). Determine the system transfer function from  $e(t)$  to  $\theta(t)$ .