編號: 134

國立成功大學 105 學年度碩士班招生考試試題

系 所:系統及船舶機電工程學系

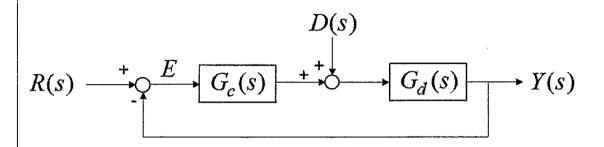
考試科目:自動控制

考試日期:0227,節次:2

第1頁,共1頁

※ 考生請注意:本試題不可使用計算機。 請於答案卷(卡)作答,於本試題紙上作答者,不予計分。 1.

- (i) Suppose a system y=S(x) is linear, where y is output and x is input. Please describe the conditions of a linear system satisfies. (15%)
- (ii) Is y=ax+b a linear system? (5%), Why? (5%)
- 2. A system is with a block diagram as below



- (i) Please find the relationship between Y(s) and R(s) (5%)
- (ii) Please find the relationship between Y(s) and D(s) (5%)
- (iii) Define the system tracking error E(s) = R(s) Y(s). Please find the relationship between E(s) and the combination of (D(s)) and R(s) (5%)
- (iv) How to reduce the error E(s) due to D(s) in steady state? (10%)
- 3. Please sketch the Bode plots for G(s). (15%) According to the definition of bandwidth, please find the bandwidth of G(s) and briefly describe what kind of the filter of G(s) is? (10%)

$$G(s) = \frac{0.5s}{1 + 0.1s}$$

4. A dynamical system is formulated by the following governing equation.

$$\ddot{x} + a_1 \dot{x} + a_2 x = b_0 \dot{u} + b_1 u$$

- (i) Find the state space formulation of this system. (10%)
- (ii) If the system parameters can be selected, please find them to satisfy the zero steady state error with respect to a unit step input. (15%)