

國立成功大學  
111學年度碩士班招生考試試題

編 號：169

系 所：電機工程學系

科 目：控制系統

日 期：0219

節 次：第 2 節

備 註：不可使用計算機

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※ 考生請注意：本試題不可使用計算機。請於答案卷(卡)作答，於本試題紙上作答者，不予計分。

- Let  $KG(s) = \frac{K(s+1)}{(s+25)(s-2)^2}$ . Sketch the root locus for  $1+KG(s)=0$ ,  $K \geq 0$ . Be sure to calculate the asymptotes and their intersection, give the arrival and departure angles of multiple roots, and find imaginary-axis crossings and the corresponding value of  $K$ , and determine the range of  $K$  for stable closed-loop system. Also, figure out values of  $K$  at multiple roots. (25%)
- A unity feedback control system has the open-loop transfer function  $KG(s) = \frac{K(s+8)^2}{s^3}$ . Apply Nyquist plot design method to find the range of  $K$  such that the closed-loop system is stable, where the Nyquist path is chosen as in Fig 1. (25%)
- For the circuit shown in Fig. 2, find the transfer function  $G(s) = V_o(s)/V_i(s)$  using nodal analysis. (25%)
- Convert the block diagram of Fig. 3 to a signal-flow graph. Use Mason's rule to find the transfer functions  $C(s)/R(s)$  for the resulting signal-flow graph. (25%)

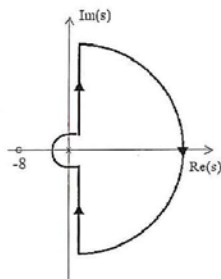


Fig. 1. Nyquist path for Problem 2.

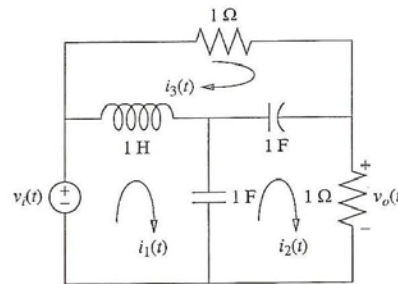


Fig. 2

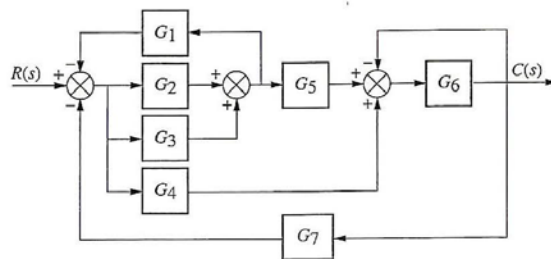


Fig. 3