

- The block diagram of a unity feedback control system is shown in Fig. 1.
 - Determine the gain margin in dB when the phase-crossover frequency $\omega_x < 10$.
 - Determine the stability of this system.
 - Draw the Bode plot of the open-loop transfer function.

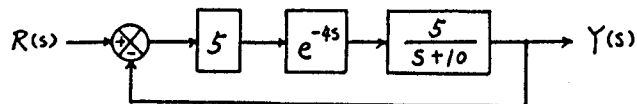


Fig. 1

- Given a system $\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -16 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ and $\begin{bmatrix} x_1(0) \\ x_2(0) \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$, $y = [1 \ 4] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$
 - Find a Lyapunov function $V(x)$ for the system with $-\dot{V}(x) = x_1^2 + 4x_1x_2 + 10x_2^2$. Determine the stability using the Lyapunov's method.

(b) Evaluate $J = \int_0^{\infty} [x_1^2(t) + 4x_2^2(t)] dt$ and $J = \int_0^{\infty} y^2(t) dt$

- Obtain the transfer function $Y(s)/R(s)$ of the system shown in Fig. 2.

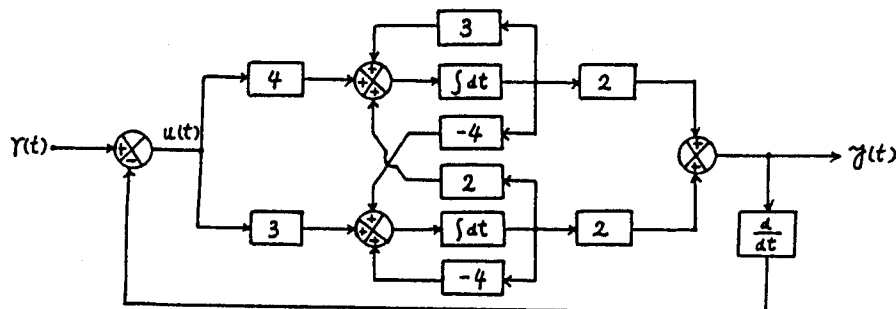


Fig. 2

- The block diagram of a second-order system is shown in Fig. 3. Suppose that the time-domain response equation of this system to the input $r(t) = 2u(t)$ is given as $c(t) = 5[1 - xe^{-yt} \sin(500t + 1)]$.
 - Calculate the values of x and y .
 - Determine the values of system parameters A , B , and D .
 - Determine the system transfer function using the parameter values.

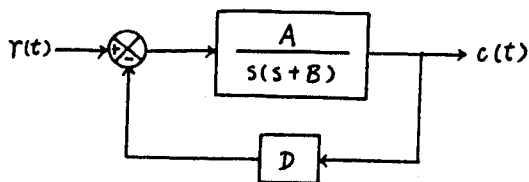


Fig. 3