

P.1 (25%) Explain following terms:

- (a) D'Alembert's principle
- (b) radius of gyration
- (c) principle of virtual work
- (d) conservative mechanical system
- (e) Coriolis acceleration

P.2 (30%) In a study of head injury against the instrument panel of a car during sudden or crash stops where lap belts without shoulder straps are used, the mechanical model shown in Figure 1 is analyzed. The hip joint O is assumed to remain fixed relative to the car, and the torso above the hip is treated as a rigid body of mass m freely pivoted at O. The center of mass of the torso is at G with the initial position of OG taken as vertical. The radius of gyration of the torso about O is k_o . If the car is brought to a sudden stop with a constant deceleration a , determine the velocity v relative to the car with which the model's head strikes the instrument panel. If the panel has a Young's modulus of E , determine the maximum deformation (δ) of the panel at the contact point and the largest impact force F . Substitute the values $m=50\text{kg}$, $\bar{r}=450\text{mm}$, $r=800\text{mm}$, $k_o=550\text{mm}$, $\theta=45\text{ deg}$, $a=10g$ and $E=1720\text{MPa}$ and compute v , δ and F .

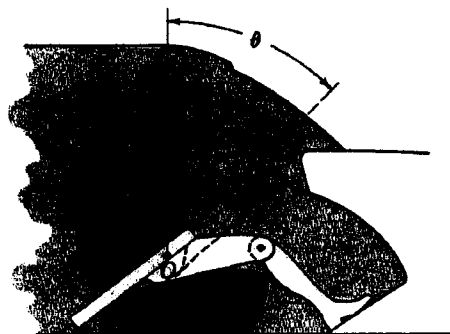


Figure 1.

P.3 (25%) The ~~amusement~~ car shown in Figure 2 which has a mass of 100kg rolls on the horizontal track with a constant speed $v=0.6\text{m/s}$ and it carries the girl who is seated on the chair mounted on the rotating rod with $r = 4\text{m}$. A geared motor drive maintains a constant angular speed $\dot{\theta} = 4 \text{ rad/s}$ of the rod. The girl has a body mass of 12kg. Determine the reactive force acted on the girl's back by the seat.

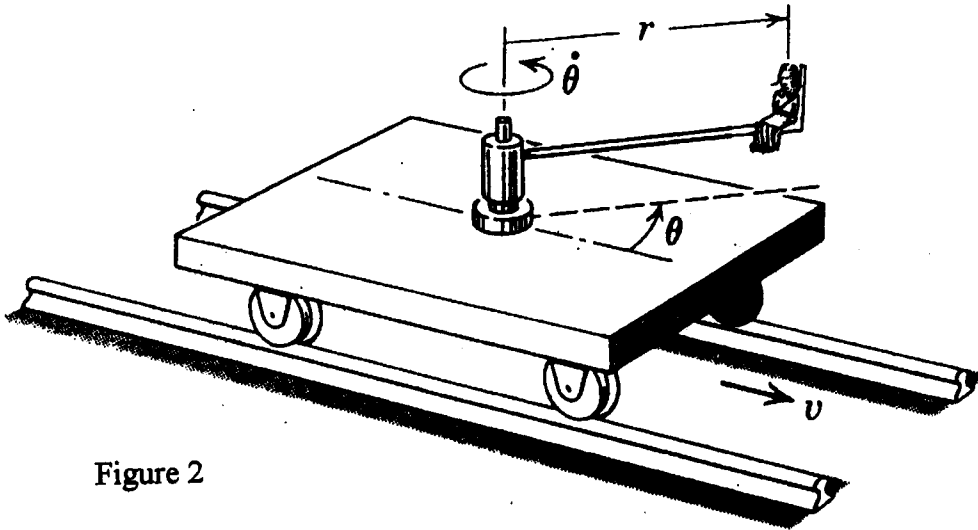


Figure 2

P. 4 (20%) The cam (Figure 3) has a shape such that the center of the roller A which follows the contour moves on a curve defined by $r = b - c \cos\theta$, where $b > c$. If the cam does not rotate, determine the magnitude of the total acceleration of A in terms of θ if the slotted arm revolves with a constant counterclockwise angular rate $\dot{\theta} = \omega$.

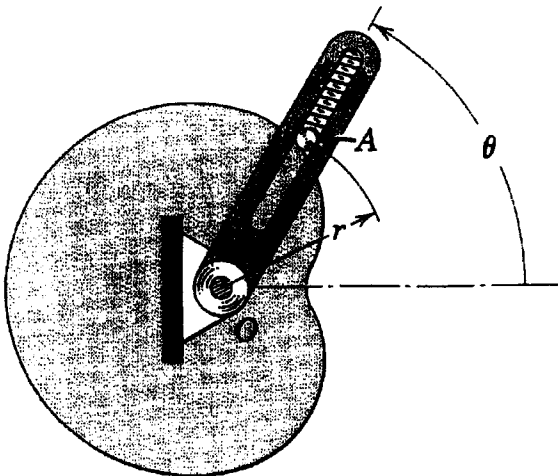


Figure 3.