編號:

190

國立成功大學九十七學年度碩士班招生考試試題

共2頁,第1頁

系所:醫學工程研究所乙組

科目:控制工程

本試題是否可以使用計算機:

□可使用 , 1√不可使用

(講命題老師勾選)

考試日期:0301,節次:2

1. (50 %) The transfer function of a system is described as following

$$\frac{y(s)}{u(s)} = \frac{s+2}{s^3 + 3s^2 - 4s - 12}$$

- (a) Please show how to check the controllability or observability of the system (5 points)
- (b) Please show how to check the system's stability (BIBO stable) (5 points)
- (c) To realize the system as a controllable canonical form $\dot{x}(t) = Ax(t) + Bu(t)$ and y(t) = Cx(t) and find the matrix A, B, and C (10 points)
- (d) Please find the state feedback u(t)=Kx to let the system eigenvalues be -1, -4,-5. (10 points)
- (e) Why the state feedback will not change the controllability, may change the observability (10 points)
- (f) If the input u(t) is impulse function, please find the system output, y(t). (10 points)

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2. (50%) The system can be described as following

$$\dot{x}(t) = Ax(t) + Bu(t)$$

$$y(t) = Cx(t)$$

A, B, and C are constant matrices. Answer the following questions.

- (a) How to find the system's transfer function? (5 points)
- (b) How to check whether the system realization is minimal realization? (5 points)

(c) If
$$A = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 2 \end{bmatrix}$$
, can you find a nonsingular matrx Q , such that QAQ^{-1}

become a diagonal matrix? If yes, please find Q matrix. If no, why? (10 points)

- (d) If (A, B) is not completely controllable, how to decompose into controllable parts and uncontrollable parts (Write down your procedure) (10 points)
- (e) How to check the system's controllability, obervability and stability? (Write down your procedure) (10 points)
- (f) How to find the state transition marix? (Write down the procedure) (5 points)
- (g) Any advantages on state variable description over on transfer function description? (5 points)